## Actuator FD40

FD40 is a compact actuator providing up to 4000N thrust, which is suitable for limited installation space. The motor can be placed on the left or right side according to requirements, and various performance options are also available.


## Features and Options

Main applications: Furniture, medical care

## Standard features:

- Input voltage: 24V DC
- Max. load: 4000N (Push) / 2000N (Pull)
- Typical speed at no load: $30.3 \mathrm{~mm} / \mathrm{sec}$
- Typical speed at full load: $4.0 \mathrm{~mm} / \mathrm{sec}(4000 \mathrm{~N}$ load)
- Stroke: 50 ~ 400mm
- Noise level: $\leqq 50 \mathrm{~dB}$
- IP level: IP42
- Preset limit switches
- Duty cycle: $10 \%$, max. 2 min. continuous operation in 20 min.
- Operating ambient temperature: $-20^{\circ} \mathrm{C} \sim+65^{\circ} \mathrm{C}$
- Certified: CE Marking, EMC Directive 2014/30/EU
- Mechanical brake


## Options:

- Enhanced motor
- Positioning signal feedback with Hall effect sensor x 2
- Mechanical push only extension tube
- PTC thermistor for thermal protection
- Motor position on right side (standard, Fig. 1) or motor position on left side (Fig.2)


Fig. 1


Fig. 2

## Performance Data

- With default motor

| Model No. | Push Max. <br> $\mathbf{( N )}$ | Pull Max. <br> $\mathbf{( N )}$ | Typical speed (mm/s) |  | Typical current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | No load | Full load | No load | Full load |  |  |
| FD40-XXDF4-XXX.XXX-XXXXXXX | 1500 | 1500 | 7.7 | 5.8 | 0.3 | 2.5 |
| FD40-XXDF8-XXX.XXX-XXXXXXX | 500 | 500 | 16 | 13.5 | 0.3 | 1.8 |

Speed vs. Load


Current vs. Load
24V DC


- With enhanced motor

| Model No. | Push Max. <br> (N) | Pull Max. <br> (N) |
| :--- | :---: | :---: |
| FD40-XXEF4-XXX.XXX-XXXXXXX | 4000 | 2000 |
| FD40-XXEF6-XXX.XXX-XXXXXXX | 3000 | 2000 |
| FD40-XXEF8-XXX.XXX-XXXXXXX | 2500 | 2000 |
| FD40-XXEH8-XXX.XXX-XXXXXXX | 1500 | 1500 |


| Typical speed (mm/s) |  | Typical current (A) |  |
| :---: | :---: | :---: | :---: |
| No load | Full load | No load | Full load |
| 8.4 | 4.0 | 0.2 | 3.3 |
| 11.9 | 6.3 | 0.2 | 3.3 |
| 15.9 | 8.1 | 0.3 | 3.3 |
| 30.3 | 14.3 | 0.4 | 3.3 |

Speed vs. Load



## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit.

The performance curves are made with typical values.


- Motor position on left side

- Installation Dimension

| Front connector code | Stroke (S) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\leqq 200 \mathrm{~mm}$ | $201 \sim 250 \mathrm{~mm}$ | $251 \sim 300 \mathrm{~mm}$ | $301 \sim 400 \mathrm{~mm}$ |
| 2 | $A \geqq \mathrm{~S}+110 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+120 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+130 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+140 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ |
| 3,6 | $\mathrm{~A} \geqq \mathrm{~S}+123 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+133 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+143 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $\mathrm{A} \geqq \mathrm{S}+153 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ |

Available stroke (S) range $=50 \sim 400 \mathrm{~mm}$
Extended length $(B)=S+A$, Retracted length (A)

## - Front connector

2: Drilled hole
(only for models with (only for models with
max. load $\leqq 2000 \mathrm{~N}$ )


3: Metal slot


6: Plastic slot (only for models with max. load $\leqq 2000$ N )


## - Rear connector

2: Metal


4: Plastic
(only for models with max. load $\leqq 2000 \mathrm{~N}$ )

D1, D2


| Front connector code | Diameter of pivot without bushing (D1) | Diameter of pivot with bushing (D2) | Width with bushing (W1) | Slot width (W2) | Slot depth <br> (H) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | Ø8, $\varnothing 10$ | $\emptyset 8$ | 22 | N/A | N/A |
| 3 | Ø8, 010 | $\emptyset 8$ | 22 | 6 | 11.5 |
| 6 | Ø8, Ø10 | N/A | N/A | 6 | 15 |
| Rear connector code | Diameter of pivot without bushing (D1) | Diameter of pivot with bushing (D2) | Width with bushing (W1) | Slot width (W2) | Slot depth <br> (H) |
| 2 | Ø8, Ø10 | Ø8 | 22 | 6 | 12 |
| 4 | Ø8, Ø10 | N/A | N/A | 6 | 12 |

- Pivot orientation of rear connectors


Remarks: As an example in $0^{\circ}$ orientation for rear connector.

| Product | Model | FD40 spec |
| :---: | :---: | :---: |
| Control box | CS1, CS2, CB3T, CB4M | - Without positioning sensor feedback <br> - 4-pin MOTECK F-type DIN plug |
|  | CF11H, CF12H | - Without positioning sensor <br> - With Moteck L3-type minifit 6-pin plug |
|  | CF11S, CF12S | - With dual Hall effect sensors <br> - With Moteck L3-type minifit 6-pin plug |
| Hand control | Depend on control box | - Powered by control box |
|  | H3B, HZ01 | - With MOTECK Direct-Cut cable TL1* |
|  | HB, H2G, HSO2, HZO2, HZO3, HZO4, HZ05, HZ06 | - With MOTECK Direct-Cut cable DL1* |
| Accessory | Switching mode power supply: TSW1, TSW4 | - With MOTECK Direct-Cut cable DL1 or TL1 |

## Remarks:

* Connect Direct-Cut cable to DC power supply and hand control directly, no control box.
- With Moteck F-type or L3-type plug (Required to be connected to the control box):
- Without Hall effect sensor


F-type 4-pin DIN plug


L3-type Minifit 6-pin plug

- With dual Hall effect sensors


F-type 6-pin DIN plug


L3-type Minifit 6-pin plug


F-type


L3-type

## Remarks:

Connect Pin (M+) to "+" \& Pin (M-) to "-" of DC power, the actuator will extend.

- With Direct-Cut cable DL1 or TL1 (NOT required to be connected to any control box):
- Hand control connector: with Moteck U-type female connector

1 drive


M1-
5-pin connector (Moteck pinout: C-DIN-51R)

2 drives


M1-
5-pin connector
(Moteck pinout: C-DIN-52R)

## Remarks:

Connect pin (M1+) to "+" \& pin (M1-) to "-" of DC power, the M1 actuator will extend.
Definition of M2 actuator is the same.

- Power plug: with Moteck S-type DIN 41529 male plug


DIN 41529 plug

- Connector for 2nd actuator: with Moteck R-type DIN 41529 female (for TL1 only)


DIN 41529 connector

- Direct-Cut cable DL1

- Direct-Cut cable TL1


Cable with Flying Leads

- Without hall effect sensors

|  | Wire color | Definition | Comments |
| :--- | :---: | :--- | :--- |
| Power <br> wires | White | DC power | Connect white wire to "Vdc +" \& black wire to "Vdc -" of DC power to <br> extend the actuator. Switch the polarity of DC input to retract it. |

- With dual hall effect sensors

| Power wires | Wire color | Definition | Comments |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Blue <br> Brown | DC power | Connect blue wire to "Vdc +" \& Brown wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it. |  |
| Signal wires | Yellow | Vin | Voltage input range: $3.5 \sim 20 \mathrm{~V}$ |  |
|  | Red | Hall 1 output | High= Input - 1.2V $( \pm 0.6 \mathrm{~V})$ <br> Low= GND <br> Hall signal data: <br> Hall effect sensor resolution: |  |
|  | Green | Hall 2 output | Model No. | Resolution (pulses/mm) |
|  |  |  | FD40-XXDF4-XXX.XXX-XXXHXXX | 7.00 |
|  |  |  | FD40-XXDF8-XXX.XXX-XXXHXXX | 3.50 |
|  |  |  | FD40-XXEF4-XXX.XXX-XXXHXXX | 7.00 |
|  |  |  | FD40-XXEF6-XXX.XXX-XXXHXXX | 4.66 |
|  |  |  | FD40-XXEF8-XXX. PXX-XXXHXXX $^{\text {a }}$ | 3.50 |
|  |  |  | FD40-XXEH8-XXX.XXX-XXXHXXX | 1.75 |
|  | Black | GND |  |  |

Ordering Key


