## Actuator FD60

FD60 is a quiet and powerful actuator up to 6000N thrust, designed for use in furniture application. Our T-control box, which can be perfectly attached and integrated to FD60, is available for customers to choose.

## Features and Options

## Main application: Furniture

## Standard features:

- Input voltage: 12V DC / 24V DC
- Max. load: 6000N (push) / 4000N (pull)
- Speed at no load: 33.3mm/sec (typical value)
- Speed at full load: 2.9mm/sec (typical value @6000N loaded)
- Stroke: 50 ~ 300mm
- Noise level: $\leqq 50 \mathrm{~dB}$
- IP level: IP42
- Preset limit switches
- Duty cycle: 10\%, max. 2 min. continuous operation in 20 min.
- Operating ambient temperature: $-20^{\circ} \mathrm{C} \sim+65^{\circ} \mathrm{C}$
- Certified: CE Marking, EMC Directive 2014/30/EU,

UL 962 Standard for Household and Commercial Furnishings.

## Options:

- Positioning signal feedback with Hall effect sensor x 1
- Positioning signal feedback with Hall effect sensor x 2
- Mechanical push only extension tube
- Mechanical brake

Performance Data

| Model No. | Push Max. <br> (N) | Pull Max. (N) | Self-locking ability <br> (N) | Typical speed (mm/s) |  | Typical current (A) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | No load | Full load | No load |  | Full load |  |
|  |  |  |  |  |  | 12V | 24V | 12V | 24V |
| FD60-XX-A4 | 6000 | 4000 | 5000 | 4.2 | 2.9 | 1.2 | 0.6 | 5.4 | 2.7 |
| FD60-XX-A6 | 4000 | 4000 | 2500 | 6.2 | 3.8 | 1.2 | 0.6 | 5.6 | 2.8 |
| FD60-XX-A8 | 3000 | 3000 | 2000 | 8.3 | 5.0 | 1.2 | 0.6 | 5.6 | 2.8 |
| FD60-XX-AG | 1500 | 1500 | 700 | 16.6 | 12.2 | 1.2 | 0.6 | 5.6 | 2.8 |
| FD60-XX-KG | 750 | 750 | 0 | 33.3 | 23.5 | 1.2 | 0.6 | 5.4 | 2.7 |
| FD60-XX-F4 | 5000 | 4000 | 5000 | 5.5 | 4.4 | 1.2 | 0.6 | 5.6 | 2.8 |
| FD60-XX-F8 | 3000 | 3000 | 2000 | 11.0 | 8.2 | 1.2 | 0.6 | 5.8 | 2.9 |



## Remarks:

* The self-locking ability is performed by short circuit the motor terminals when the actuator is powered off. All MOTECK compatible control boxes are designed with this feature. Mechanical brake in push direction is available upon request, to further enhance the self-locking ability to maximum load.
** The typical speed or typical current means the average value neither upper limit nor lower limit.
The performance curves are made with typical values.


## Dimensions

- Available stroke (S) range $=50 \sim 300 \mathrm{~mm}( \pm 3 \mathrm{~mm})$
- Extended length $(B)=$ Retracted length $(A)+$ Stroke (S)
- Retracted length (A)

| Front connector code |  | 1,5,8 |
| :---: | :---: | :---: |
| Rear connector code | 2,3,7 |  |
| $\mathbf{1 , 2}$ | $A \geqq S+188 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $A \geqq S+160 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ |
| 5 (with crank function) | $A \geqq S+198 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ | $A \geqq S+170 \mathrm{~mm}( \pm 3 \mathrm{~mm})$ |

- Drawing



Note: As an example in $0^{\circ}$ orientation for rear connector.

- Front connector
1: Plastic

2: Drilled hole with brass bushing

$\varnothing 10$
3: Drilled hole

5: Metal
7: Drilled hole with nylon bushing
8: Enhanced metal


| Front connector <br> code | Diameter of pivot <br> without bushing (D1) | Diameter of pivot <br> with bushing (D2) | Width <br> with bushing (W1) | Slot width <br> (W2) | Slot depth <br> (H) |
| :---: | :--- | :--- | :---: | :---: | :---: |
| 1 | $ø 8, \varnothing 10, \varnothing 12$ | N/A | N/A | 10 | 20 |
| 2 | N/A | N/A | N/A | N/A | N/A |
| 3 | $ø 8, \varnothing 10, \varnothing 12, \varnothing 14$ | $\varnothing 8, \varnothing 10$ | 26 | N/A | N/A |
| 5 | $ø 8, \varnothing 10, \varnothing 12$ | $\varnothing 8, \varnothing 10$ | 32 | 10 | 20 |
| 7 | N/A | N/A | N/A | N/A | N/A |
| 8 | $\varnothing 10, \varnothing 12$ | $\varnothing 8, \varnothing 10$ | 31.5 | 8 | 19.5 |

## - Rear connector

1: Plastic
2: Metal
5: Metal (with crank function)


| Rear connector <br> code | Diameter of pivot <br> without bushing (D1) | Diameter of pivot <br> with bushing (D2) | Width <br> with bushing (W1) | Slot width <br> (W2) | Slot depth <br> (H) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\varnothing 8, \varnothing 10, \varnothing 12$ | N/A | N/A | 6,10 | 17 |
| 2 | $\varnothing 8, \varnothing 10, \varnothing 12$ | $ø 8, \varnothing 10$ | 32 | 6,10 | 17 |
| 5 | $\varnothing 14.5$ | N/A | N/A | N/A | N/A |

Compatibility

| Product | Model | FD60 spec |
| :---: | :---: | :---: |
| Control box | T-control, CS1, CS2, CB3T, CB4M, CBT2, CBTR | - Without positioning sensor <br> - With Moteck F-type 4-pin DIN plug |
|  | CF11H, CF12H | - Without positioning sensor <br> - With Moteck L3-type minifit 6-pin plug |
|  | CB3T-SY, CB4M-S, CB4M-B | - With dual Hall effect sensors for positioning <br> - With Moteck F-type 6-pin DIN plug |
|  | CB3T-SYD | -12V DC motor <br> - With dual Hall effect sensors for positioning <br> - With Moteck F-type 6-pin DIN plug |
|  | CF11S, CF12S | - With dual Hall effect sensors for positioning <br> - With Moteck L3-type minifit 6-pin plug |
|  | CF15 | - 24 V DC motor, A 4 option <br> - With Moteck L3-type minifit 6-pin plug |
| Hand control | Depend on control box | - Powered by control box |
|  | H3B, HZ01 | - With Moteck Direct-cut power cable TL2 * |
|  | HB, H2G, HZO2, HZ03, HZO4, HZ05, HZ06, HSO2 | - With Moteck Direct-cut power cable DL2 * |
| Accessory | TSW1 switching mode power supply | - With Moteck Direct-cut power cables DL2 or TL2 |

## Remarks:

* Connect Direct-cut power cable to DC power supply and hand control directly, no control box.

With Moetck F-type or L3-type plug (Required to be connected to the control box):

- Without positioning feedback


F-type 4-pin DIN plug


L3-type Minifit 6-pin plug


F-type plug


L3-type plug

## Note:

1. Connect $\mathrm{M}+$ to "Vdc +" \& M - to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it.
2. The pin definition of Hall 2 is provided only when dual Hall sensors is selected.

With Direct-cut power cable DL2 or TL2 (NOT required to be connected to any control box):

- Hand control connector: with Moteck U-type female connector
- 1 drive


M1+
5-pin connector
(Moteck pinout: C-DIN-51H)

- 2 drives


5-pin connector
(Moteck pinout: C-DIN-52H)

Note: Connect M1+ to "Vdc +" \& M1- to "Vdc -" of DC power to extend the M1 actuator. Switch the polarity of $D C$ input to retract it. Definition of the M2 actuator is the same.

- Power plug: with Moteck R-type DIN 41529 male plug

- Connector for 2nd actuator: with Moteck R-type DIN 41529 female connector (for TL2 only)



R-type male plug


U-type female connector


R-type female connector

- Cable length
- With Direct-cut power cable DL2

- With Direct-cut power cable TL2


Unit: mm

## Cable with Flying Leads

- Basic, without positioning feedback.

|  | Wire color | Definition | Descriptions |
| :--- | :--- | :--- | :--- |
| Power <br> wires | White | DC Power | Connect white wire to "Vdc +" \& black wire to "Vdc -" of DC power <br> to extend the actuator. Switch the polarity of DC input to retract it. |

- With single Hall effect sensor for positioning

| Power wires | Wire color | Definitions | Descriptions |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Blue Brown | DC Power | Connect blue wire to "Vdc +" \& brown wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it. |  |
| Signal wires | Yellow | Vin | Voltage input range: $3.5 \sim 20 \mathrm{~V}$ |  |
|  | Red | Hall output | $\text { High= Input - } 1.2 \mathrm{~V}( \pm 0.6 \mathrm{~V})$ <br> Low= GND <br> Hall signal data: <br> Hall effect sensor resolution: |  |
|  |  |  | Model No. | Resolution (pulses/mm) |
|  |  |  | FD60-XX-A4-XXX.XXX-CXX-HSX | 10.0 |
|  |  |  | FD60-XX-F4-XXX.XXX-CXX-HSX | 10.0 |
|  |  |  | FD60-XX-A6-XXX.XXX-CXX-HSX | 6.67 |
|  |  |  | FD60-XX-A8-XXX.XXX-CXX-HSX | 5.0 |
|  |  |  | FD60-XX-F8-XXX.XXX-CXX-HSX | 5.0 |
|  |  |  | FD60-XX-AG-XXX.XXX-CXX-HSX | 2.50 |
|  |  |  | FD60-XX-KG-XXX.XXX-CXX-HSX | 1.25 |
|  | Black | GND |  |  |

- With dual Hall effect sensors for positioning


Ordering Key


## Certifications

FD60 actuator is compliant with the following regulations, in terms of the essential conformity requirements of EMC Directive of 2014/30/EU.

| Emission | Immunity |
| :---: | :---: |
| EN 55014-1:2006+A1:2009+A2:2011 | EN 55014-2:1997+A1:2001+A2+:2008 Catagory I |

