## Actuator ID12

ID12 has the same performance of load capability, speed, and power consumption as ID10. However, ID12 features its square outer tube, which makes it easy to install and apply the external reed sensor on demand.


## Features and Options

## Main applications: Industrial

## Standard features:

- Input voltage: 12 / 24 / 48V DC
- Max. rated load: 3,500N (ACME) / 7,000N (Ball Screw)
- Max. static load: 4,500N (ACME) / 13,600N (Ball Screw)
- Max. speed at no load: $72.1 \mathrm{~mm} / \mathrm{sec}$ (Typical value)
- Stroke: 100 / 150 / 200 / 300 / 450 / 600mm
- IP Level: IP66, IP69K
- Overload protection by clutch
- Aluminum outer tube
- Stainless steel extension tube
- Color: Black gearbox and motor
- Power cord length: 250mm (with bare wires)
- Duty cycle: $25 \%$, max. 2 min. continuous operation in 8 min.
- Operating ambient temperature: $-25^{\circ} \mathrm{C} \sim+65^{\circ} \mathrm{C}$
- Certified: CE Marking, EMC Directive 2014/30/EU


## Options:

- Positioning signal feedback with Hall effect sensor x 1
- Analog and absolute positioning feedback with Potentiometer (POT)
- Preset limit switches (LT), to stop motor automatically at both stroke ends by cutting power.
- External adjustable reed sensor. NC-type ( i.e. normal close) is default.

And NO-type (i.e. normal open) is also available, please indicate to sales window if required.

- Manual drive socket (MD, can be driven by hand with a 8 mm hex bit screwdriver or electric screwdriver)
- Mounting bracket (MB30)


## Performance Data

ACME type

- 12V DC motor

| Model No. | Gear <br> ratio | Push/Pull <br> Max. ( | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load |  |  |
| ID12-12-10-A-XXX | $10: 1$ | 1500 | 33.5 | 26.7 | 2.6 | 17.6 |
| ID12-12-20-A-XXX | $20: 1$ | 2500 | 16.8 | 14.3 | 2.6 | 13.2 |
| ID12-12-40-A-XXX | $40: 1$ | 3500 | 8.4 | 7.3 | 2.6 | 11.0 |

Speed vs. Load


Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.
- 24 V DC motor

| Model No. | Gear ratio | Push/Pull <br> Max. (N) | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load | No load | Full load |
| ID12-24-10-A-XXX | 10:1 | 1500 | 33.5 | 26.7 | 1.6 | 8.8 |
| ID12-24-20-A-XXX | 20:1 | 2500 | 16.8 | 14.3 | 1.6 | 6.6 |
| ID12-24-40-A--XXX | 40:1 | 3500 | 8.4 | 7.3 | 1.6 | 5.5 |



Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit.

The performance curves are made with typical values.

- 48V DC motor

| Model No. | Gear ratio | Push/Pull <br> Max. (N) | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load | No load | Full load |
| ID12-48-10-A-XXX | 10:1 | 1500 | 36.5 | 29.1 | 1.4 | 3.6 |
| ID12-48-20-A-XXX | 20:1 | 2500 | 17.8 | 15.3 | 0.8 | 2.4 |
| ID12-48-40-A-XXX | 40:1 | 3500 | 8.6 | 7.8 | 0.5 | 2.1 |



Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit.

The performance curves are made with typical values.

## Ball Screw type

- 12V DC motor

| Model No. | Gear ratio | Push/Pull <br> Max. (N) | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load | No load | Full load |
| ID12-12-05-B-XXX | 5:1 | 2500 | 67.1 | 47.2 | 3.4 | 26.4 |
| ID12-12-10-B-XXX | 10:1 | 3500 | 33.5 | 26.7 | 2.6 | 17.6 |
| ID12-12-20-B-XXX | 20:1 | 4500 | 16.8 | 14.3 | 2.6 | 13.2 |
| ID12-12-30-B-XXX | 30:1 | 6000 | 11.2 | 9.8 | 2.6 | 12.1 |
| ID12-12-40-B-XXX | 40:1 | 7000 | 8.4 | 7.4 | 2.6 | 11.0 |

Speed vs. Load


Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.
- 24V DC motor

| Model No. | Gear ratio | Push/Pull <br> Max. (N) | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load | No load | Full load |
| ID12-24-05-B-XXX | 5:1 | 2500 | 67.1 | 47.2 | 2.6 | 13.2 |
| ID12-24-10-B-XXX | 10:1 | 3500 | 33.5 | 26.7 | 1.6 | 8.6 |
| ID12-24-20-B-XXX | 20:1 | 4500 | 16.8 | 14.3 | 1.6 | 6.6 |
| ID12-24-30-B-XXX | 30:1 | 6000 | 11.2 | 9.8 | 1.6 | 6.1 |
| ID12-24-40-B-XXX | 40:1 | 7000 | 8.4 | 7.4 | 1.6 | 5.5 |

Speed vs. Load


Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.
- 48V DC motor

| Model No. | Gear ratio | Push/Pull <br> Max. (N) | Typical Speed (mm/s) |  | Typical Current (A) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | No load | Full load | No load | Full load |
| ID12-48-05-B-XXX | 5:1 | 2500 | 72.1 | 57.5 | 0.5 | 5.5 |
| ID12-48-10-B-XXX | 10:1 | 3500 | 36.5 | 29.1 | 0.5 | 3.6 |
| ID12-48-20-B-XXX | 20:1 | 4500 | 17.8 | 15.3 | 0.5 | 2.4 |
| ID12-48-30-B-XXX | 30:1 | 6000 | 11.7 | 10.3 | 0.5 | 2.5 |
| ID12-48-40-B-XXX | 40:1 | 7000 | 8.6 | 7.8 | 0.5 | 2.1 |

Speed vs. Load


Current vs. Load


## Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit.

The performance curves are made with typical values.

## Dimensions

## ACME type

- Extended length (B) = Retracted length (A) + Stroke (S)
- Retracted length (A)

| Option | Stroke (S) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{1 0 0}\left(\mathbf{4}^{\prime \prime}\right)$ | $\mathbf{1 5 0}\left(6^{\prime \prime}\right)$ | $\mathbf{2 0 0}\left(\mathbf{8}^{\prime \prime}\right)$ | $\mathbf{3 0 0}\left(\mathbf{1 2 ^ { \prime \prime } )}\right.$ | $\mathbf{4 5 0}\left(\mathbf{1 8 ^ { \prime \prime } )}\right.$ | $\mathbf{6 0 0}(\mathbf{2 4 \prime )}$ |
| Standard | 266 | 316 | 366 | 466 | 666 | 816 |
| With positioning | 306 | 356 | 406 | 506 | 706 | 856 |
| With LT | 362 | 412 | 462 | 612 | 762 | 912 |

(Tolerance: $\pm 5 \mathrm{~mm}$ )

## - Drawing

- Standard (without Limit switch nor positioning feedback)

- With Limit switches (LT) or positioning feedback


Unit: mm

## Ball Screw type

- Extended length (B) = Retracted length (A) + Stroke (S)
- Retracted length (A)

| Option | Stroke (S) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{1 0 0}\left(\mathbf{4}^{\prime \prime}\right)$ | $\mathbf{1 5 0}\left(6^{\prime \prime}\right)$ | $\mathbf{2 0 0}\left(\mathbf{8}^{\prime \prime}\right)$ | $\mathbf{3 0 0}\left(12^{\prime \prime}\right)$ | $\mathbf{4 5 0}\left(18^{\prime \prime}\right)$ | $\mathbf{6 0 0}\left(\mathbf{2 4 ^ { \prime \prime } )}\right.$ |
| Standard | 319 | 369 | 419 | 519 | 719 | 869 |
| With positioning | 359 | 409 | 459 | 559 | 759 | 909 |
| With LT | 415 | 465 | 515 | 665 | 815 | 965 |

(Tolerance: $\pm 5 \mathrm{~mm}$ )

## - Drawing

- Standard (without Limit switch nor positioning feedback)

- With Limit switches (LT) or positioning feedback


Unit: mm

## - Front connector

## ACME type

- Standard (without Limit switch nor positioning feedback)



## Ball Screw type

- Standard (without Limit switch nor positioning feedback)

- Rear connector

- Pivot orientation of rear connector


Note: As an example in $0^{\circ}$ pivot of rear connector.


- Manual drive socket (MD)
- Compatible with IP54 option and 5, 10 or 20 to 1 gear ratio.
- Not applicable to IP66, IP69K, Limit switch and/or Potentiometer option.
- Power wires outlet at motor cap. (Refer to page 8 \& 9)
- Please refer to "ID12 User Guide" for operation steps.


Drive the hex socket on the motor shaft by screwdriver or electric screwdriver with 8 mm hex bit.

## Compatibility

| Product |  | Model | ID12 spec |
| :---: | :---: | :---: | :---: |
| Control box | CI10 |  | - 24 V motor <br> - With limit switches option <br> - Without positioning sensor feedback |
|  | CIS1 |  | - 24 V motor <br> - With single Hall effect sensor for positioning |
|  | CIS2 |  | - 12 V motor <br> - With single Hall effect sensor for positioning |
|  | CIS3 |  | - 24 V motor <br> - With Potentiometer for positioning |

## Wiring

- Standard (without Limit switch nor positioning feedback)

Gear ratio: 5:1, 10:1, 20:1

|  | Wire color | Definition | Comments |
| :---: | :---: | :---: | :---: |
| Power wires | Red | DC power | Connect red wire to "Vdc +" \& black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it. |

Gear ratio: 30:1, 40:1

| Wire color |  |  |  |  |  |  |  | Definition | Comments |
| :---: | :---: | :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Power <br> wires | Red | DC power | Connect red wire to "Vdc -" \& black wire to "Vdc +" of DC power to <br> extend the actuator. Switch the polarity of DC input to retract it. |  |  |  |  |  |  |

- With Limit switches

|  | Wire color | Definition | Comments |
| :--- | :---: | :--- | :--- |
| Power <br> wires | Red | Black | DC power | | Connect red wire to "Vdc +" \& black wire to "Vdc -" of DC power to |
| :--- |
| extend the actuator. Switch the polarity of DC input to retract it. |

- With Potentiometer (POT) absolute positioning feedback


The resistance between blue and white wires increases when the actuator extends, and decreases when it retracts.


- With single Hall effect sensor positioning feedback

|  | Wire color | Definition | Comments |
| :---: | :---: | :---: | :---: |
| Power wires | Red <br> Black | DC power | Connect red wire to "Vdc +" \& black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it. |
| Signal wires | Blue | GND |  |
|  | White | Vin | Voltage input range: 3.5 ~ 20V |
|  | Yellow | Hall | Hall effect sensor resolution: 20ppi, $1.27 \mathrm{~mm} /$ pulse ( 0.787 pulses $/ \mathrm{mm}$ ) Output voltage of signal (DATA) = Vin Hall signal data: |

## Remarks:

With external reed sensors, select either yellow or white wire as common point, and the other one will be signal output.


## Certifications

The ID12 actuator is compliant with the following regulations, in terms of the essential conformity requirements of EMC Directive of 2014/30/EU.

| Emission | Immunity |
| :--- | :--- |
| EN 61000-6-3:2007+A1:2011 | EN 61000-6-1:2007 <br> IEC 61000-4-2:2008 <br> IEC 61000-4-3:2006+A1:2007+A2:2010 <br> IEC 61000-4-8:2009 |

Ordering Key


More information about usage is provided in ID12 User Guide, which can be downloaded from Moteck website.

